

DEPLOYMENT LOG for IceCube STRING # 47

	Donlarmant Start 27			
	Deployment Start: at	Da on 1/22/07	a variable de la companya del companya de la companya del companya de la companya	
	Deployment End: at 367:5700 1/23/07			
	Target depth (DOM60): 245	60 m Final depth:	2551.5	
ustin: J-9-11 B-1-105 Sebastian				
	S. Tree B. Maryanare	Deployment Crew		
	Position	First Shift	Second Shift	
(4)	Shift lead	Albrecht Karle	7. Ham	
	DOM install 1 (high)	Phil 2.0-		
	DOM install 2 (low)	Karthile		
	DOM supply 1 / DOM install 3	Hogar. O	140	
	DOM supply 2 / floater	Ryan 0	н	
1	Albrecht.			
6	to Michelande			
RANDT		Justin Vanden brouche Michelangele D'Agastino	J.Vandenbrovche	
	475	Mark Krasbergo		
7	10013100	of shift change:	n	
7	Luc Han	8 -1.	1h	
1	LUSIUNS	M. 2 M2	Odrill	

Hole Handover			
☐ Drill data reviewed	8		
□ maximum drift in	x: □	plot	
☐ maximum drift in	y: □	plot	
□ maximum depth:_	- Contraction		
□ minimum radius:_		plot	
□ plot of predicted ra	adius vs depth	and time	
☐ Hole dimensions verif	ied	Time:	
Drill Lead:			
	name / sig	gnature / date	
Deployment Lead:	nome / sic	gnature / date	
	name / sig	gnature / date	
□ Handover complete			
		4 	
Hole Logging (skip if not applicable)			
☐ Logger drop started	Time:	Speed:Speed:	
☐ Logging started	Time:	Speed:	
☐ Logging ended	1 IIIIC		2 V
☐ Estimated hole lifetime:			
► Must reach targ	et depth by _	on	

Deployment Startup
Time:
 ☑ Cable winch anchored and □ operational ☑ Tower winch operational ☑ Tie off verified ☑ Yellow rope verified
 Deployment monitoring system (PTS) operational □ DDB# Pressure sensors on hand: Paro and Keller, with backups Laser ranger, tape measure (metric) on hand
☐ Bleeder string installed (on quad connectors inside cable reel drum)
 □ Uphole pressure system on hand: Setra sensor and cable ☑ DOMs placed in racks ☑ Weight stack on hand: weights (5) and 2 m cable ☑ 17 m string extension steel cable on hand
Safety checks complete (□ 1 st shift □ 2 nd shift) □ Crew safety briefing □ E-stop locations identified □ TOS evacuation procedures reviewed □ Mustering point identified □ Snow mobile driver(s):
☐ CPR trained:
☐ Food runners: ☐ Food runners:
□ End of Main Cable brought into TOS and secured
Cable end attachments

□ Food runners:			
call galley at 65521			
☐ End of Main Cable brought into TOS and secured			
Cable end attachments			
☐ Measure well depth: (48,962 delayning 51, 47.5 in will take ☐ Weights (5) attached (ordered by allrecht —)			
Weights (5) attached (ndered by threcht,)			
☐ Weight cable attached (weight stack complete) Time:			
3/37			



Photos: DOM ids (\square long \square short); connectors (\square long \square short)			
DOM position 60 (T, Long) DOM id: TP 490313 Walnusish			
(T, Long) Walnusish			
Bottom shackle connected to weight stack Top shackle connected to 17 m steel cable Photos: whole view			
DOM position 59 DOM id: UP 69/424			
(U, Short) Cable mark: 1,5			
 ☑ Bøttom shackle connected to 17 m cable ☑ Tøp shackle connected to Yale grip ☑ Main cable end taped to 17 m steel cable Photos: ☐ phi orientation ☐ whole view 			
Breakout 30 Time: 9:/0			
Depth: - LongDOM □ connector O-ring in place and □ lubed □ breakout O-ring in place and □ lubed □ connected			
- ShortDOM □ connector O-ring in place and □ lubed □ breakout O-ring in place and □ lubed □ connected Loose pigtails taped to cable			
Paro Serial #: 98172 Nipple on off Connected Operational Air pressure [PSI]: 9.47 Cable mark: 2 m Distance to DOM59: 1,055 m above Mark Square Squa			



Photos: DOM ids (\square long \square short); connectors (\square long \square short)			
DOM position 58	DOM id: TP <u>54023</u> /		
/	ark: /9m		
☐ Bottom shackle connected	1 11 19		
☐ Top clutch connected at \lim Bow OK \rightarrow \square clutch zip t			
Photos: □ phi orientation □			
DOM position 57	DOM id: UP <u>540254</u>		
(U, Short) Cable m	ark: 35		
☐ Bottom shackle connected ☐ Top clutch connected at lin	nk #_ /8 Δ(57-58):_ /(,945		
\square Bow OK $\rightarrow \square$ clutch zip t	ied		
Photos: □ phi orientation □	whole view		
Breakout 29	Time:		
	Now 9:28		
- LongDOM	Last b/o		
☐ connector O-ring in pla			
□ breakout O-ring in place□ connected	ce and \square lubed Depth:		
	Payout 51.5/		
- ShortDOM			
☐ connector O-ring in pla			
□ breakout O-ring in place□ connected	ce and \square lubed		
☐ Loose pigtails taped to cab	le		
*	8		
□ All c	ear to lower cable ⊙		



Photos: DOM ids (□ long □ short); connectors (□ long □ short)		
DOM position 56	DOM id: TP540203	
(T, Long) Cable mark: 53m		
Bottom shackle connected ☐ Top clutch connected at link #/ // ☐ Bow OK → ☐ clutch zip tied ☐ Photos: ☐ phi orientation ☐ whole view	Δ(56-57): <u>/6,938</u>	
DOM position 55 (U, Short) Cable mark: 69	DOM id: UP 6 8 /4/2	
 □ Bottom shackle connected □ Top clutch connected at link # □ Bow OK → □ clutch zip tied Photos: □ phi orientation □ whole view 	Δ(55-56): /6.970	
Breakout 28	Time:	
- LongDOM □ connector O-ring in place and □ lubed □ breakout O-ring in place and □ lubed □ connected	Now 9:44 Last b/o Δt [min] Depth: Paro 72 8 3 Payout 84, 79	
- ShortDOM □ connector O-ring in place and □ lubed □ breakout O-ring in place and □ lubed □ connected		
☐ Loose pigtails taped to cable		
□ All clear to lower cab	ole 😊	



Photos: DOM ids (\square long \square short); connectors (\square long \square short)			
DOM position 54		DOM id: TP 540/21	
(T, Long)	Cable mark: 86,5		
\square Bow OK $\rightarrow \square$ el	ected at link #	Δ(54-55): <u>/(, ,957</u>	
DOM position 53	9. gr	DOM id: UP 68/4/6	
(U, Short)	Cable mark: <i>NA</i>	DOW Id. 01 <u>@17 1/6</u>	
 ☑ Bottom shackle of ☑ Top clutch conne ☑ Bow OK → ☑ cl Photos: ☐ phi orien 	connected ected at link #	Δ(53-54):_// ₀ ,9/0	
Breakout 27		Time:	
Dieakout Zi		i iiie.	
□ breakout O-ri□ connected- ShortDOM□ connector O-ri	ring in place and □ lubed ing in place and □ lubed ring in place and □ lubed ing in place and □ lubed ing in place and □ lubed	Now /6.01 Last b/ο Δt [min] Depth: Paro /67,01 Payout //7,94	
☐ Loose pigtails tap	ped to cable		
	□ All clear to lower cab		
The state of the s	I All Clear to lower car	JC ♥	



Photos: DOM ids (\square long \square short); connectors (\square long \square short)			
DOM position 52	DOM id: TP <u>5402 49</u>		
(T, Long) Cable mark: 2 M			
 ☑ Bottom shackle connected ☑ Top clutch connected at link # ☑ Bow OK → ☑ clutch zip tied Photos: ☐ phi orientation ☐ whole view 	Δ(52-53): 16.955		
DOM position 51 (U, Short) Cable mark: 137 m	DOM id: UP 1/4382		
 Bottom shackle connected Top clutch connected at link # Bow OK → □ clutch zip tied Photos: □ phi orientation □ whole view 	Δ(51-52): <u>N6,952</u>		
Breakout 26	Time:		
 LongDOM □ connector O-ring in place and □ lubed □ breakout O-ring in place and □ lubed □ connected 	Now 10:/5 Last b/o Δt [min] Depth: Paro 141.47 Payout 151.53		
 ShortDOM □ connector O-ring in place and □ lubed □ breakout O-ring in place and □ lubed □ connected 			
☐ Loose pigtails taped to cable			
☐ All clear to lower ca	ble ☺		



Photos: DOM ids (□ long □ short); connect	tors (□ long □ short)
DOM position 50	DOM id: TP644325
(T, Long) Cable mark: 155	
Bottom shackle connected	A/50 51). // 0/0
 □ Top clutch connected at link # 20 □ Bow OK → □ clutch zip tied 	Δ(50-51): /6,9/8
Photos: □ phi orientation □ whole view	
The state of the s	☐ Vertical distance:
s .	BROKEN CONNECTOR
DOM position 49	DOM id: UP 64423
(U, Short) Cable mark: /// m	-
Bottom shackle connected	the Dermane med
☐ Top clutch connected at link # 19	the Dermane need to imp Δ(49-50): Hoggi
Bow OK $\rightarrow \Box$ clutch zip tied	16,994
Photos: \Box phi orientation \Box whole view	
☐ Curved distance around DOM:	☐ Vertical distance:
Dunalsaut 25	T .
Breakout 25	Time:
· · · · · · · · · · · · · · · · · · ·	Now
- LongDOM	Last b/o
☐ connector O-ring in place and ☐ lubed	
☐ breakout O-ring in place and ☐ lubed	Depth:
□ connected	Paro <u>1/6-77</u> Payout 185-94
- ShortDOM	rayout [vze]
☐ connector O-ring in place and ☐ lubed	d
□ breakout O-ring in place and □ lubed	
☐ Loose pigtails taped to cable	
□ All clear to lower o	able



Photos: DOM ids (\square long \square short); connectors (\square long \square short)			
DOM position 48	DOM id: TP <u>54020</u> 7		
(T, Long) Cable mark: #88			
 □ Bøttom shackle connected □ Top clutch connected at link # □ Bow OK → □ clutch zip tied Photos: □ phi orientation □ whole view 	Δ(48-49): <u>/6,939</u>		
DOM position 47	DOM id: UP <u>6Y 425</u> 2		
(U, Short) Cable mark: NA	DOWNG. OF $\frac{\sqrt{67}}{\sqrt{3}}$		
Bottom shackle connected □ Top clutch connected at link # □ Bow OK → □ clutch zip tied Photos: □ phi orientation □ whole view	Δ(47-48): /6,960		
Breakout 24	Time:		
 LongDOM connector O-ring in place and □ lubed breakout O-ring in place and □ lubed connected ShortDOM connector O-ring in place and □ lubed breakout O-ring in place and □ lubed connected 	Now /0:43 Last b/o Δt [min] Depth: Paro 2/0.05 Payout 2/8.52		
	s •		
☐ Loose pigtails taped to cable	* ,		
□ All clear to lower ca	ole 🕲		



Photos: DOM ids (□ long □ short); connector	rs (long short)
DOM position 46	DOM id: TP 6 4436/
(T, Long) Cable mark: 222	,
 □ Bottom shackle connected □ Top clutch connected at link # □ Bow OK → □ clutch zip tied Photos: □ phi orientation □ whole view 	Δ(46-47): <u>16,922</u>
DOM position 45	DOM id: UP 5 140 150
(U, Short) Cable mark: 239	
 Bottom shackle connected Top clutch connected at link # Bow OK → □ clutch zip tied Photos: □ phi orientation □ whole view 	Δ(45-46): <u>//4,984</u>
Breakout 23	Time:
 LongDOM □ connector O-ring in place and □ lubed □ breakout O-ring in place and □ lubed □ connected ShortDOM 	Now <u>10-54</u> Last b/o Δt [min] Depth: Paro <u>244-66</u> Payout <u>252-11</u>
 □ connector O-ring in place and □ lubed □ breakout O-ring in place and □ lubed □ connected 	
☐ Loose pigtails taped to cable	
□ All clear to lower ca	ble ⊕





DI DOLL'I	(-11 - 111111 -	/
Photos: DOM ids (\square long \square short); connectors (\square long \square short)		
DOM position 44		DOM id: TP <u>5H012</u> 7
(T, Long)	Cable mark: 257	a a g
☐ Bottom shackle		11 045
/ -	nected at link #	Δ(44-45): <u>/</u> (, , 945
$\square \text{Bow OK} \to \square \text{ or}$	2007 - 1000 Harris	
Photos: ☐ phi orie	ntation \square whole view	
DOM position 43		DOM id: UP <u>5 H 0/3</u> 2
DOM position 43	Cable marks 173	DOW Id. OF <u>3 (4 07)2</u>
(U, Short)	Cable mark: 273	
Bottom shackle	connected	
	nected at link #	Δ(43-44): <u>//, 902</u>
\square Bow OK $\rightarrow \square$	Elutch zip tied	,
	ntation whole view	
Total Control of the		
Breakout 22		Time:
26		NI DAG
7 7014		Now//:05
- LongDOM		Last b/o
	ring in place and □ lubed	Δt [min]
	ring in place and □ lubed	Depth:
□ connected		Paro <u>279.35</u>
G1 - D G1 (Payout 285.96
- ShortDOM		
	ring in place and □ lubed	
- L- Si	ring in place and □ lubed	
□ connected		
□ Loogo nicteila t	and to apple	
☐ Loose pigtails to	aped to cable	
-		а.
10		
	☐ All clear to lower cab	ole 😊





Photos: DOM ids (\square long \square short); connectors (\square long \square short)		
DOM position 42		DOM id: TP 1, 44307
(T, Long) Ca	able mark: <u>29/</u>	
Bottom shackle com	nected	
Top clutch connecte		Δ(42-43): 16,968
Bow OK → © clutc		,
Photos: phi orientati	on □ whole view	
DOM position 41		DOM id: UP 644234
	able mark: <i>30</i> 7	
	, ·	10
☑ Bøttom shackle com☑ Top clutch connecte		Δ(41-42): 16,994
Bow OK → Clutc		<u> </u>
Photos: phi orientati	•	
- 404	er J	
Breakout 21		Time:
		Now // //
- LongDOM		Last b/o
1	g in place and \Box lubed in place and \Box lubed	Δt [min] Depth:
□ connected	in place and \(\square \) luocd	Paro 3/3.75
		Payout 319.47
- ShortDOM		
1	g in place and □ lubed	
☐ breakout O-ring☐ connected☐	in place and □ lubed	
Connected		
☐ Loose pigtails taped	to cable	
,		
*		
* ,,	All clear to lower cab	le 😊



Photos: DOM ids (☐ long ☐ short); connector	s (□ long □ short)
DOM position 40	DOM id: TP 5H 0/33
(T, Long) Cable mark: 325	
Bottom shackle connected	
Top clutch connected at link #	Δ(40-41): <u>16.963</u>
Bow OK → © clutch zip tied	1 -1 -1
Photos: ☐ phi orientation ☐ whole view	
DOM position 39	DOM id: UP <u>54 0234</u>
(U, Short) Cable mark: 342	2011 Id. 01 3// (43/
Bottom shackle connected Top clutch connected at link #	1/20 10) 11 938
Bow OK \rightarrow \square clutch zip tied	Δ(39-40): 16,938
Photos: \Box phi orientation \Box whole view	
Breakout 20	Time:
	Now // 30
- LongDOM	Last b/o
☐ connector O-ring in place and ☐ lubed	Δt [min]
☐ breakout O-ring in place and ☐ lubed	Depth:
□ connected	Paro <u>347.98</u> Payout <i>MMM</i> 352.84
- ShortDOM	1 ayout 107
\Box connector O-ring in place and \Box lubed	
☐ breakout O-ring in place and ☐ lubed	<u>,</u>
□ connected	8
☐ Loose pigtails taped to cable	
- Loose piguins taped to eable	, ,
	2
	2
	*
□ All clear to lower cal	ole ©



	1
1	
VIII.	١.,
1	1

Photos: DOM ids (\square long \square short); connectors (\square long \square short)		
DOM position 38	DOM id: TP <u>64439</u> /	
(T, Long) Cable mark: 358		
 □ Bottom shackle connected □ Top clutch connected at link # □ Bow OK → □ clutch zip tied Photos: □ phi orientation □ whole view 	Δ(38-39): /6,950	
DOM position 37	DOM id: UP 5 H 0230	
(U, Short) Cable mark: 375		
 ☑ Bottom shackle connected ☑ Top clutch connected at link # ☑ Bow OK → ☑ clutch zip tied Photos: ☐ phi orientation ☐ whole view 	Δ(37-38): <u> [6,96]</u>	
Breakout 19	Time:	
 LongDOM connector O-ring in place and □ lubed breakout O-ring in place and □ lubed connected ShortDOM connector O-ring in place and □ lubed breakout O-ring in place and □ lubed connected 	Now //; 40 Last b/o Δt [min] Depth: Paro 382.42 Payout 386, 45	
☐ Loose pigtails taped to cable		
□ All clear to lower cab	ole ③	



Photos: DOM ids (\Box long \Box short); connector	s (□ long □ short)
DOM position 36		DOM id: TP /2 \ \ \ \ \ \ \ \ \ \ \ \ \ \ \ \ \ \
(T, Long)	Cable mark: 393	DOM Id. 11 (4) 7/75
(1, Long)	Cable Hark.	
Bottom shackle	connected	
Top clutch conne	ected at link #	Δ(36-37): 16,974
Bow OK → ac		,
	ntation whole view	
4		BROKEN CONNECTOR
DOM position 35		DOM id: UP LY 4258
(U, Short)	Cable mark: 4 / 0	*
□ Bottom shackle		8/ 207
/ -	ected at link #	Δ(35-36): <u>//, 993</u>
\square Bow OK $\rightarrow \square$ c		
Photos: phi orier	ntation \square whole view	
Breakout 18		Time:
		Now_/2:0/
- LongDOM		Last b/o
-	ring in place and lubed	Δt [min]
	ing in place and \Box lubed	Depth:
□ connected	mg m place and - laced	Paro 4/8, 02
Comiccica		Payout 421.09
- ShortDOM		Tayout 40410
	ring in place and □ lubed	
	ing in place and \Box lubed	
	ing in place and - labed	
- connected		
☐ Loose pigtails ta	ned to cable	
_ Loose piguins u	p = 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0	
☐ Put two Kellers (one is for backup) in bucket	et of water/ice mix
	17	
	☐ All clear to lower cal	ole ©



Photos: DOM ids (☐ long ☐ short); connectors	s (□ long □ short)
DOM position 34		DOM id: TP 64 4423
(T, Long)	Cable mark: 437	
 □ Bottom shackle of □ Top clutch connection □ Bow OK → □ cl Photos: □ phi orien 	cted at link #	Δ(34-35): <u>16,947</u>
DOM position 33		DOM id: UP 644402
(U, Short)	Cable mark: 444	DOWN I.O. 01 1/1/005
(c, chort)	oabio mark	# 2
Bøttom shackle of Top clutch conneBow OK → ☐ clPhotos: ☐ phi orien	ceted at link #	Δ(33-34): <u>16.933</u>
Breakout 17		Time:
 breakout O-ri connected ShortDOM connector O- 	ring in place and □ lubeding in place and □ lubed	Now 12:11 13:17 Last b/o At [min] Depth: Paro Payout
Loose pigtails tap	ped to cable	
	☐ All clear to lower cal	nle 🙃

	IceCube String Deployment Log	String 47 Actual Says The V4	13
Photos:	DOM ids (☐ long ☐ short); connecto		V
DOM pos	sition 32	DOM id: TP	
(T, Long)	Cable mark:	M35cd & Deglayme	1
Botto	m shackle connected	disens deflayme	A
	lutch connected at link #/8	Δ(32-33): /6 · 9/	
archive and	OK → ☐ clutch zip tied ☐ phi orientation ☐ whole view	*	
110000	parameter a vinore view		
DOM pos		DOM id: UP 6 1/44 Z	Contract
(U, Short)	Cable mark: 478m	674448	
	m shackle connected lutch connected at link # /8	Δ(31-32): /6.9/4	
0 573			
Photos:	phi orientation whole view	come da	
Breakout	t 16	placed DOM Time:	
		Now 21:40	
- LongI	OOM		
	nnector O-ring in place and □ lubed eakout O-ring in place and □ lubed		
	nnected		
C1	DOM		
- ShortI	DOM nnector O-ring in place and □ lubed		
1/ 0	eakout O-ring in place and \(\square\$ lubed		
/	nnected		

☐ All clear to lower cable ☺

 \square Loose pigtails taped to cable



Photos: DOM ids (☐ long ☐ short); connecto	ors (long short)
DOM position 30	DOM id: TP 6 7 4 2 4 5
(T, Long) Cable mark:	
Bottom shackle connected Top clutch connected at link # Bow OK → □ clutch zip tied Photos: □ phi orientation □ whole view DOM position 29 (U, Short) Cable mark: 5/2	Δ(30-31): 16.92 MVD again BROKEN CONNECT DOM id: UP 6 4425 9
 □ Bottom shackle connected □ Top clutch connected at link # □ Bow OK → □ clutch zip tied Photos: □ phi orientation □ whole view 	Δ(29-30): // //
Breakout 15	
 LongDOM □ connector O-ring in place and □ lubed □ breakout O-ring in place and □ lubed □ connected 	
- ShortDOM ☐ connector O-ring in place and ☐ lubed ☐ breakout O-ring in place and ☐ lubed ☐ connected	
☐ Loose pigtails taped to cable	
Thermistor ☐ Present ☐ Distance to DO! Keller ☐ Connected ☐ Operational Ser.#: ○ 1, 0 1, 7 4 1 ☐ Cable mark: ~ 5 / 3 ☐ Distance to DO! ☐ All clear to lower cases.	Air pressure [PSI]: 3.50 stance to DOM29: 976 m Move poin 29



Photos: DOM ids (\square long \square short); connectors (\square long \square short)		
DOM position 28	DOM id: TP 644451	
(T, Long) Cable mark: 529	0 0,1	
Bottom shackle connected ☐ Top clutch connected at link #	Δ(28-29): 16,981	
DOM position 27	DOM id: UP 64 4256	
(U, Short) Cable mark: 546		
 □ Bottom shackle connected □ Top clutch connected at link # □ Bow OK → □ clutch zip tied Photos: □ phi orientation □ whole view 	Δ(27-28): /6,955	
Breakout 14	Time:	
 LongDOM □ connector O-ring in place and □ lubed □ breakout O-ring in place and □ lubed □ connected ShortDOM 	Now 2://) Last b/o Δt [min] Depth: Paro 556,26 Keller 575,48 Payout 554,27	
 □ connector O-ring in place and □ lubed □ breakout O-ring in place and □ lubed □ connected 		
☐ Loose pigtails taped to cable		
□ All clear to lower ca		



Photos: DOM ids (\square long \square short); connectors (\square long \square short)		
DOM position 20		DOM id: TP6/432/
(T, Long)	Cable mark: 563	DOWN II. 11 (1/2/1/20)
		6,
☐ Bottom shackl		
Top clutch con	/	Δ(26-27): [6, 969]
Bow OK → □		6.0
Filotos. pili off	entation whole view	
DOM position 2	5	DOM id: UP 6H 7522
(U, Short)	Cable mark: 580	
Bottom shackle	1940	1/05 00) 1/ 9/19
/ -	inected at link #	Δ(25-26): // ₆ , 949
☐/Bow OK → ☐ Photos: ☐ phi ori	entation \square whole view	*
	citation - whole view	
Breakout 13		Time:
-		Now_2:22
- LongDOM		Last b/o
_	O-ring in place and □ lubed	Δt [min]
☐ breakout O	ring in place and □ lubed	Depth;
\Box connected		Paro 596, 48
		Keller_589.96
- ShortDOM		Payout 587.75
	O-ring in place and \(\Box \) lubed	
connected	ring in place and □ lubed	
- connected		
☐ Loose pigtails	taped to cable	
1 0	,	
	.e	a
	☐ All clear to lower cab	le [©]



Photos: DOM ids (\square long \square short); connectors (\square long \square short)		
DOM position 24	1	DOM id: TP644407
(T, Long)	Cable mark: 597	,
\square Bow OK $\rightarrow \square$	nected at link #	Δ(24-25): <u>/6,939</u>
DOM position 23 (U, Short)	Cable mark:	DOM id: UP <u>6 \ \ \ \ \ \ \ \ \ \ \ \ \ \ \ \ \ \ </u>
D∕Bow OK → 🗵	nected at link #	Δ(23-24): <u>//</u> , 940
Breakout 12		Time:
□ breakout O□ connected- ShortDOM□ connector O	O-ring in place and \square lubed ring in place and \square lubed O-ring in place and \square lubed ring in place and \square lubed	Now 2:39 Last b/o Δt [min] Depth: Paro 129.74 Keller 624.36 Payout 421.39
☐ Loose pigtails	taped to cable	
	☐ All clear to lower cab	ole 😊



Photos: DOM ids	$(\Box \text{ long } \Box \text{ short}); \text{ connectors}$	s (□ long □ short)
DOM position 22		DOM id: TP 644279
(T, Long)	Cable mark: 63	
Dottom choolele		
Bottom shackle	rected at link #	Δ(22-23): 16, 928
\square /Bow OK $\rightarrow \square$ /		$\Delta(22-23)$. $(0, 190)$
	entation	
F	, , , , , , , , , , , , , , , , , , , ,	*
DOM position 21	1 4	DOM id: UP <u>67 4282</u>
(U, Short)	Cable mark:	
Bottom shackle	connected	
	nected at link #	Δ(21-22): /6,9/8
Bow $OK \rightarrow V$		
l .	entation whole view	
-		
Breakout 11		Time:
		Now 2:5%
- LongDOM		Now 2.56 Last b/o
<u>-</u>	o-ring in place and □ lubed	Δt [min]
□ breakout O-	ring in place and \Box lubed	Depth:
□ connected		Paro 659/8
		Keller 659.73
- ShortDOM	v	Payout 65509
1	oring in place and □ lubed ring in place and □ lubed	
□ connected	ring in place and \(\sigma\) lubed	
☐ Loose pigtails to	aped to cable	
	a a w	
5		
, s		
20		
5	☐ All clear to lower cab	ole 🕲
1		





Photos: DOM ids (\square long \square short); connectors (\square long \square short)			
DOM position 20	DOM id: TP <u>6/441</u> 9		
(T, Long) Cable mark: 465			
Bottom shackle connected			
☐ Top clutch connected at link #	Δ(20-21):/6,974		
Bow $OK \rightarrow \Box$ clutch zip tied			
Photos: □ phi orientation □ whole view			
☐ Curved distance around DOM: ☐	Vertical distance:		
DOM position 19	DOM id: UP 5# 0190		
(U, Short) Cable mark: \(\lambda 82 \)			
Bøttom shackle connected			
☐ Top clutch connected at link #	Δ(19-20): 16,948		
\square Bow OK $\rightarrow \square$ clutch zip tied	-(··)· <u>-/··//</u>		
Photos: □ phi orientation □ whole view			
☐ Curved distance around DOM: ☐	Vertical distance:		
Breakout 10	Time:		
\$	Now 3/01		
- LongDOM	Last b/o		
☐ connector O-ring in place and ☐ lubed	Δt [min]		
☐ breakout O-ring in place and ☐ lubed	Depth:		
	Paro <u>693.33</u>		
Ch aut DOM	Keller <u>693.19</u> Payout <i>688.53</i>		
- ShortDOM ☐ connector O-ring in place and ☐ lubed	Payout <i>688.53</i>		
□ breakout O-ring in place and □ lubed			
□ connected			
☐ Loose pigtails taped to cable			
□ All clear to lower ca	ble ⊚		





Photos: DOM ids (□ long □ short); connectors (□ long □ short)		
DOM position 18	DOM id: TP(6 P/4/7)	
(T, Long) Cable mark: NA	-	
 ☑ Bottom shackle connected ☑ Top clutch connected at link # ☑ Bow OK → ☑ clutch zip tied Photos: ☐ phi orientation ☐ whole view 	Δ(18-19): <u>] [</u>	
DOM position 17	DOM id: UP 64 43/4	
(U, Short) Cable mark: 7/6 m	-	
 □ Bottom shackle connected □ Top clutch connected at link # □ Bow OK → □ clutch zip tied Photos: □ phi orientation □ whole view 	Δ(17-18): /6,967	
Breakout 9	Time:	
 LongDOM connector O-ring in place and □ lubed breakout O-ring in place and □ lubed connected ShortDOM connector O-ring in place and □ lubed breakout O-ring in place and □ lubed connected 	Depth: Paro 727.78 Keller 728.57 Payout 721.99	
☐ Loose pigtails taped to cable		
□ All clear to lower c	able ©	





Photos: DOM ids (\square long \square short); connectors (\square long \square short)			
DOM position 16	DOM id: TP 67 4283		
(T, Long) Cable mark: 733	BROKEN CONNECTER		
Bottom shackle connected			
☐ Top clutch connected at link #	Δ(16-17): /6.972		
Bow OK → □ clutch zip tied	_(,		
Photos: phi orientation whole view	W.		
DOM position 15	DOM id: UP <u>6.P / 388</u>		
(U, Short) Cable mark: 150	50Wild. C1 (1) 1 000		
h			
Bottom shackle connected			
Top clutch connected at link #	Δ(15		
Filotos. pin orientation whole view			
Breakout 8			
I DOM			
- LongDOM			
☐ connector O-ring in place and ☐ lubed☐ breakout O-ring in place and ☐ lubed☐	Depin:		
	Paro 76201		
	Keller 76/89		
- ShortDOM	Payout 755.38		
☐ connector O-ring in place and ☐ lubed			
☐ breakout O-ring in place and ☐ lubed			
☐ Loose pigtails taped to cable	e .		
Loose pigians taped to caole			
* *** *** *** *** *** *** *** *** ***			
□ All -14-1	ahla o		
☐ All clear to lower ca	able 😉		





Photos: DOM ids (\square long \square short); connectors (\square long \square short)		
DOM position 14	DOM id: TP <u>5 H0227</u>	
(T, Long) Cable mark:	ži	
■ Bøttom shackle connected		
☐ Top clutch connected at link #	Δ(14-15): /b. 994	
Bow OK → □ clutch zip tied	<u> </u>	
Photos: □ phi orientation □ whole view		
	P(1)	
DOM position 13	DOM id: UP <u>5/40228</u>	
(U, Short) Cable mark: 784		
☑ Bøttom shackle connected		
Top clutch connected at link #	Δ(13-14): 16,967	
Bow OK → □ clutch zip tied		
Photos: □ phi orientation □ whole view		
Breakout 7	Time:	
	Now_3: 40	
- LongDOM	Last b/o	
\Box connector O-ring in place and \Box lubed	Δt [min]	
☐ breakout O-ring in place and ☐ lubed	Depth:	
□ connected	Paro 796.36	
ShortDOM	Keller 797./6	
- ShortDOM ☐ connector O-ring in place and ☐ lubed	Payout	
□ breakout O-ring in place and □ lubed	*	
□ connected		
☐ Loose pigtails taped to cable		
y 8		
☐ All clear to lower cab	ole 😊	



Photos: DOM ids (\square long \square short); connectors (\square long \square short)		
DOM position 12		DOM id: TP6Y 4467
(T, Long)	Cable mark: 801	3 · · / · /
\square /Bow OK $\rightarrow \square$ /cl	cted at link #	Δ(12-13): <u>//₄, 958</u>
DOM position 11		DOM id: UP 644426
(U, Short)	Cable mark: 8/8	<u> </u>
Bottom shackle cTop clutch conneBow OK → □ cl	connected ected at link #	Δ(11-12): <u>/6,975</u>
Breakout 6		Time:
 □ breakout O-ri □ connected ShortDOM □ connector O-re 	ring in place and □ lubed ng in place and □ lubed ring in place and □ lubed ng in place and □ lubed bed to cable	Now 4:50 Last b/o At [min] Depth: Paro 830.60 Keller 830.6/ Payout 922,54
	☐ All clear to lower cabl	0.0
	- All clear to lower cabl	ʊ ⋓



Photos: DOM ids (Photos: DOM ids (\square long \square short); connectors (\square long \square short)		
DOM position 10		DOM id: TP <u>4 P /3 97</u>	
(T, Long)	Cable mark: §35	 	
(1, 2019)	ousio mana g-2		
Bottom shackle	connected		
Top clutch conn	ected at link #	Δ(10-11): 16,968	
Bow OK → © c	Name of the last o		
	ntation \square whole view		
DOM position 9		DOM id: UP 67 4288	
(U, Short)	Cable mark: 85λ	2 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1	
/	a a		
Bottom shackle	connected		
□ Top clutch conn	ected at link #	Δ(9-10): 16,947	
\square Bow OK $\rightarrow \square$ c	lutch zip tied	2	
	ntation whole view		
3 - S			
Breakout 5		Time:	
		Na 4 'N	
I DOM	8	Now 4:0]	
- LongDOM		Last b/o	
	ring in place and □ lubed	Δt [min]	
	\Box in place and \Box lubed	Depth:	
□ connected		Paro 8/4 8 \$	
		Keller 865.87	
- ShortDOM		Payout_ <i>§55.93</i>	
	-ring in place and \Box lubed		
☐ breakout O-r	ring in place and \Box lubed	s = -	
connected			
☐ Loose pigtails ta	ped to cable	2	
	•		
	a a		
*			
	□ All clear to lower cab	ole 😊	



Photos: DOM ids (□ long □ short); connectors (□ long □ short) DOM position 8 (T, Long) Bottom shackle connected □ Top clutch connected at link # □ Bow OK → □ clutch zip tied Photos: □ phi orientation □ whole view DOM position 7 (U, Short) Bottom shackle connected □ Top clutch connected at link # □ Bow OK → □ clutch zip tied DOM id: UP 674370 Δ(7-8): 16.955
Top clutch connected □ Top clutch connected at link # Δ(8-9): //ω. //ω □ Bow OK → □ clutch zip tied Photos: □ phi orientation □ whole view DOM position 7 (U, Short) □ Bottom shackle connected □ Top clutch connected at link # Δ(7-8): //ω. //ω.
□ Top clutch connected at link # Δ(8-9): // (8-9): // (8-9): // (8-9): // (8-9): // (8-9): // (8-9): // (8-9): // (8-9): // (8-9): // (8-9): // (8-9): // (8-9): // (8-9): // (8-9): // (8-9): // (8-9): // (8-9): // (8-9): // (8-9): // (8-9): // (8-9): // (8-9): // (8-9): // (8-9): // (8-9): // (8-9): // (8-9): // (8-9): // (8-9): // (8-9): // (8-9): // (8-9): // (8-9): // (8-9): // (8-9): // (8-9): // (8-9): // (8-9): // (8-9): // (8-9): // (8-9): // (8-9): // (8-9): // (8-9): // (8-9): // (8-9): // (8-9): // (8-9): // (8-9): // (8-9): // (8-9): // (8-9): // (8-9): // (8-9): // (8-9): // (8-9): // (8-9): // (8-9): // (8-9): // (8-9): // (8-9): // (8-9): // (8-9): // (8-9): // (8-9): // (8-9): // (8-9): // (8-9): // (8-9): // (8-9): // (8-9): // (8-9): // (8-9): // (8-9): // (8-9): // (8-9): // (8-9): // (8-9): // (8-9): // (8-9): // (8-9): // (8-9): // (8-9): // (8-9): // (8-9): // (8-9): // (8-9): // (8-9): // (8-9): // (8-9): // (8-9): // (8-9): // (8-9): // (8-9): // (8-9): // (8-9): // (8-9): // (8-9): // (8-9): // (8-9): // (8-9): // (8-9): // (8-9): // (8-9): // (8-9): // (8-9): // (8-9): // (8-9): // (8-9): // (8-9): // (8-9): // (8-9): // (8-9): // (8-9): // (8-9): // (8-9): // (8-9): // (8-9): // (8-9): // (8-9): // (8-9): // (8-9): // (8-9): // (8-9): // (8-9): // (8-9): // (8-9): // (8-9): // (8-9): // (8-9): // (8-9): // (8-9): // (8-9): // (8-9): // (8-9): // (8-9): // (8-9): // (8-9): // (8-9): // (8-9): // (8-9): // (8-9): // (8-9): // (8-9): // (8-9): // (8-9): // (8-9): // (8-9): // (8-9): // (8-9): // (8-9): // (8-9): // (8-9): // (8-9): // (8-9): // (8-9): // (8-9): // (8-9): // (8-9): // (8-9): // (8-9): // (8-9): // (8-9): // (8-9): // (8-9): // (8-9): // (8-9): // (8-9): // (8-9): // (8-9): // (8-9): // (8-9): // (8-9): // (8-9): // (8-9): // (8-9): // (8-9): // (8-9): // (8-9): // (8-9): // (8-9): // (8-9): // (8-9): // (8-9): // (8-9): // (8-9): // (8-9): // (8-9): // (8-9): // (8-9): // (8-9): // (8-9): // (8-9): // (8-9): // (8-9): // (8-9): // (8-9): // (8-9): // (8-9): // (8-9)
□ Top clutch connected at link # Δ(8-9): // (8-9): // (8-9): // (8-9): // (8-9): // (8-9): // (8-9): // (8-9): // (8-9): // (8-9): // (8-9): // (8-9): // (8-9): // (8-9): // (8-9): // (8-9): // (8-9): // (8-9): // (8-9): // (8-9): // (8-9): // (8-9): // (8-9): // (8-9): // (8-9): // (8-9): // (8-9): // (8-9): // (8-9): // (8-9): // (8-9): // (8-9): // (8-9): // (8-9): // (8-9): // (8-9): // (8-9): // (8-9): // (8-9): // (8-9): // (8-9): // (8-9): // (8-9): // (8-9): // (8-9): // (8-9): // (8-9): // (8-9): // (8-9): // (8-9): // (8-9): // (8-9): // (8-9): // (8-9): // (8-9): // (8-9): // (8-9): // (8-9): // (8-9): // (8-9): // (8-9): // (8-9): // (8-9): // (8-9): // (8-9): // (8-9): // (8-9): // (8-9): // (8-9): // (8-9): // (8-9): // (8-9): // (8-9): // (8-9): // (8-9): // (8-9): // (8-9): // (8-9): // (8-9): // (8-9): // (8-9): // (8-9): // (8-9): // (8-9): // (8-9): // (8-9): // (8-9): // (8-9): // (8-9): // (8-9): // (8-9): // (8-9): // (8-9): // (8-9): // (8-9): // (8-9): // (8-9): // (8-9): // (8-9): // (8-9): // (8-9): // (8-9): // (8-9): // (8-9): // (8-9): // (8-9): // (8-9): // (8-9): // (8-9): // (8-9): // (8-9): // (8-9): // (8-9): // (8-9): // (8-9): // (8-9): // (8-9): // (8-9): // (8-9): // (8-9): // (8-9): // (8-9): // (8-9): // (8-9): // (8-9): // (8-9): // (8-9): // (8-9): // (8-9): // (8-9): // (8-9): // (8-9): // (8-9): // (8-9): // (8-9): // (8-9): // (8-9): // (8-9): // (8-9): // (8-9): // (8-9): // (8-9): // (8-9): // (8-9): // (8-9): // (8-9): // (8-9): // (8-9): // (8-9): // (8-9): // (8-9): // (8-9): // (8-9): // (8-9): // (8-9): // (8-9): // (8-9): // (8-9): // (8-9): // (8-9): // (8-9): // (8-9): // (8-9): // (8-9): // (8-9): // (8-9): // (8-9): // (8-9): // (8-9): // (8-9): // (8-9): // (8-9): // (8-9): // (8-9): // (8-9): // (8-9): // (8-9): // (8-9): // (8-9): // (8-9): // (8-9): // (8-9): // (8-9): // (8-9): // (8-9): // (8-9): // (8-9): // (8-9): // (8-9): // (8-9): // (8-9): // (8-9): // (8-9): // (8-9): // (8-9): // (8-9): // (8-9): // (8-9): // (8-9): // (8-9): // (8-9)
Bow OK → □ clutch zip tied Photos: □ phi orientation □ whole view DOM position 7 (U, Short) Cable mark: MM 886 □ Bottom shackle connected □ Top clutch connected at link # Δ(7-8): 16.955
Photos: □ phi orientation □ whole view DOM position 7 (U, Short) Cable mark: MM 886 □ Bottom shackle connected □ Top clutch connected at link # Δ(7-8): 16.955
 (U, Short) Cable mark: 486 Bottom shackle connected Top clutch connected at link # Δ(7-8): 16.955
 (U, Short) Cable mark: 486 Bottom shackle connected Top clutch connected at link # Δ(7-8): 16.955
Bottom shackle connected Top clutch connected at link # $\Delta(7-8)$: 16.955
Top clutch connected at link # $\Delta(7-8)$: 16.955
Top clutch connected at link # $\Delta(7-8)$: 16.955
Bow OK → □ clutch zip tied
Photos: □ phi orientation □ whole view
Breakout 4
Now 4:/3
- LongDOM Last b/o
□ connector O-ring in place and □ lubed \(\Delta t \) [min] \(\Delta t \)
☐ breakout O-ring in place and ☐ lubed ☐ Depth: ☐ connected Paro \$99,07
□ connected Paro <u>899, 07</u> Keller 899 3 2
- ShortDOM Payout 889, 40
\Box connector O-ring in place and \Box lubed
☐ breakout O-ring in place and ☐ lubed
□ Loogo nictails taned to aphle
☐ Loose pigtails taped to cable
□ All clear to lower cable ⊚



p		
Photos: DOM ids ($(\Box \log \Box \text{ short}); \text{ connector}$	rs (\square long \square short)
DOM position 6		DOM id: TP 691405
(T, Long)	Cable mark:904	
☑ Bottom shackle	connected	17
-	ected at link #	$\Delta(6-7): 1/4.949$
Bow OK → Bo	flutch zip tied	
Photos: □ phi orie	ntation \square whole view	
4,000		* C.C. harman
DOM position 5		DOM id: UP <u>644248</u>
(U, Short)	Cable mark: 120	
☑ Bottom shackle		11 000
Top clutch conn		$\Delta(5-6): 16,988$
Bow OK → Do	-	
Photos: □ phi orie	ntation \square whole view	
*		
Breakout 3		Time:
		Now 4:25
- LongDOM		Now 4:25 Last b/o
	-ring in place and □ lubed	Δt [min]
	ring in place and □ lubed	Depth:
□ connected		Paro 933.50
		Keller 935.47
- ShortDOM		Payout 923.//
	-ring in place and □ lubed	Tayout [K), (
	ring in place and \Box lubed	
□ connected	ing in place and \Box racea	
Connected		
☐ Loose pigtails ta	aned to cable	
Loose pigtans to	iped to caole	
9		
_	☐ All clear to lower ca	ble 🙃
E	_ / til Oldal to lowel ou	NIC W



s (□ long □ short)
DOM id: TP 64 4337
N/A 5). 1/ 9/9
$\Delta(4-5): 1/2, 9/9$
DOM id: UP 644374
t
1/2 1). 1/ 231
$\Delta(3-4): 16.931$
Time:
Now 4:35
Last b/o
Δt [min]
Depth:
Paro <u>967.53</u>
Keller 96, 90
Payout 956.58
Ε.
z.
ole 😊



Photos: DOM ids (\square long \square short); connectors (\square long \square short)		
DOM position 2	<i>S D) , , , , , , , , , ,</i>	DOM id: TP540243
(T, Long)	Cable mark: 97]	DOW IG. 11 <u>5μ σα (.)</u>
(1, Long)	Cable mark	
☑ Bottom shackle		
☐ Top clutch conn	ected at link #	$\Delta(2-3)$: 16.973
\square Bow OK $\rightarrow \square$ c		
Photos: phi orien	ntation whole view	
DOM position 1		DOM: dall District Al
DOM position 1	Oakla mandu	DOM id: UP 6H 7506
(U, Short)	Cable mark:	
☑ Bottom shackle	connected	
Top clutch conn	ected at link #	Δ(1-2): 16,917
□ Bow OK → □ c		
Photos: phi ories	ntation \square whole view	" #
Breakout 1		Time:
		Now 4:45
- LongDOM		Last b/o
□ connector O	ring in place and □ lubed	Δt [min]
☐ breakout O-1	ring in place and \Box lubed	Depth:
☐ connected		Paro 1081-84
e s		Keller 1064. 14
- ShortDOM		Payout 490.2/
	-ring in place and □ lubed	
100	ring in place and □ lubed	
☐ I oogo nigtoilg to	nad to cable	
☐ Loose pigtails ta	ped to capic	
No second Paro no	more	
	☐ Group photo	
	☐ All clear to lower cal	ole 😊



Uphole Pressure Sensor (Setra)

After DOM1 is safely under the surface (> 50 m)

	Time:
☐ Stop the cable winch	s ·
	£ - 25
☐ Lower Setra pressure sensor into hole	,
	7,
☐ Distance to Setra from floor:	
	2
☐ Setra readout verified with monitoring system	
☐ Well depth from Setra:	
A TO THE MAN	
□ Well depth from laser: 48.962	just after
- 401.	an I installed
If the two well depth measurements agree:	110000
± 2	98,078 n after
☐ Switch to Setra well depth in monitoring system	all the rate
sa e e e e e e e e e e e e e e e e e e e	Duff was installo
	Time: 5:50

Now the String Drop begins



2000. 42

2200 a

6 4 I	
String	Dron
Juliu	DIUL

The target depth is 2450 m

Switch cable winch to computer control		Switch	cable	winch	to	computer	contro
----------------------------------------	--	--------	-------	-------	----	----------	--------

☐ Speed: Time: Depth: 1225

☐ Speed: Time: Depth:

☐ Speed: Time: Depth:

☐ Speed: Time: Depth: ☐ Speed: Time: Depth:

☐ Speed: Time: Depth:

Depth Monitorina (log on the fly – do not stop for this)

Depth by Paro ¹	Time	Well depth ¹	Depth by cable marks ²	Depth by Payout¹	Δdepth P-K¹
-1000 m					
4500 m	6:11	47.376	1483	1477.55	-4.38
2000 m	6:44	46.431	1980	1969.48	-6.43
-2100 m			The last transport of		
2200 m	0:56	46.073	9180	2166.76	-8.68
2300 m	The second of the College Coll	The latest district the state of the state o			
-2400 m	Paragraph of the Control of the Cont				

¹Read off monitoring screen

(at DOM59) -17 m = $\frac{-15.432}{}$ (at DOM60) ²Cable mark offset = 1,5 17.132 (from p.4)

☐ Switch to manual control @ 2400 m

☑ Well depth

(a) 2420:

(a) 2440: 49

2445.36 before anchoring

Position string at target depth of 2450 m

✓ String secured with Yale grip and anchor chain

Time: 7:52



Absol	ute	depth	with	bottom	Paro
		. Sat			

(depth in *meters* and pressure in *PSI*)

☐ Distance from Paro to DOM60:

$$d_{Paro-DOM59} = 1.055 \text{ (from p. 4)}$$

$$d_{Paro-DOM60} = (d_{Paro-DOM59} + 17) m = 19.187 \leftarrow insert below 17.132$$

☐ Convert Paro pressure to string depth:

$$K = 3.78151 \cdot 10^{-6}$$
 /PSI (compressibility of aerated water)

(use 6 decimals for exp's)

Ambient pressure (from p. 4): $P_0 =$ _____PSI \rightarrow exp(-KP₀) = _____

Pressure reading (from screen): $P = ____PSI \rightarrow exp(-KP) = _____$

Subtract exponentials → = _____

× 1.85947·10⁵

Paro depth in water \rightarrow = m

Add distance to DOM60 (above) -> + _____ m

Add well depth \rightarrow + m

Depth of bottom DOM \rightarrow = _____ m

Final depth estimates

◄----- read off deployment screen ------

Time:	Paro		Keller		Payout		Cable marks	
Reading	3428.3	PSI	2690	PSI	2413,1	m	2449.3	m
Offset	10.07	PSI	-3.5	PSI	-1.6	m	-15.5	m
Well depth	45	. 3	m		This space is intentionally left blank			
Dist. to DOM60		m		m				
DEPTH (DOM60)	2551.5	كاليط	2486	0	241407	•	24 64.8	

Time: 7:52 245(-17)

Final depth (DOM60) 7551.5



Deployment Closeout				
Log entries complete				
String safely secured				
☐ Hole covered and secured				
Equipment safely shutdown and secured				
Deployment data OK (in database)				
□ Site cleanup				
Deployment crew dismissed				
☐ String deployment complete				
Time: 7158 Date: 1/23/07				
Shift Lead: 19m/km				
Logger:				
PTS Lead: Justin Vandenbrouch / Will name/signature				
Deployment Manager:				
Safety Officer:				
IceCube On-ice Lead:				



Michelangelo)

IceCube Deployment Monitoring Check Sheet (IDMCS)

Justin Sebastian
B-1-105
J-9-11 61765

Version 4.0 December 12, 2006

Kurt Woschnagg, UCB

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General instructions

- ► Read through this entire document before deployment starts.
- ▶ Deployment monitoring is done with a computer (housed in the TOS) running drill/deployment monitoring software (by Chuck Rentmeesters) with a GUI for readout and manual inputs. All deployment sensor data and manual inputs are logged and saved on disk by this system.
- ► For each manual entry into the monitoring interface (marked **ENTER** below), also make a note in the logbook (marked *Logbook* below).
- ► For each entry in the logbook, include time and name (initials).
- ▶ Write down as much useful information you can think of (it *will* all be needed sooner or later).

Measurement instructions

- ▶ All vertical measurements are relative to the floor of the tower (not the lip of the kick board).
 - Measure well depth from this level.
 - Take cable mark readings at this level.
- ➤ The location of a DOM on a string (for distance measurements) is defined as the position of the center of the sphere (at the equator defined by the harness).
- ▶ When taking a cable mark reading, estimate the location to nearest cm (0.01 m) with closest cable marks and tape measure.
- ▶ The location of a Paro is defined at the bottom of its body (at the little hole with the nipple).
- ▶ The location of a Keller is defined at the row of holes in the black plastic nose cap.
- ► The distance between a pressure sensor and the nearest DOM is positive/negative if the unit is above/below the DOM.
- ▶ Well depth is measured with a laser ranger (if possible), or with a tape measure (if not).
- ▶ The unit used for all distances and depths during deployment is **meters**.

Screen Tab: TOS ▶ Deployment

▶ Sensors/Graph

This is the main tab used during deployment monitoring. No input required on this tab.

Pressure/Depth of String Current and ambient (air) pressures, and the corrected depths at DOM60. **Spacing/Depth Comparison** Difference in depth from pressure data. *Should be stable during deployment!*

Velocity

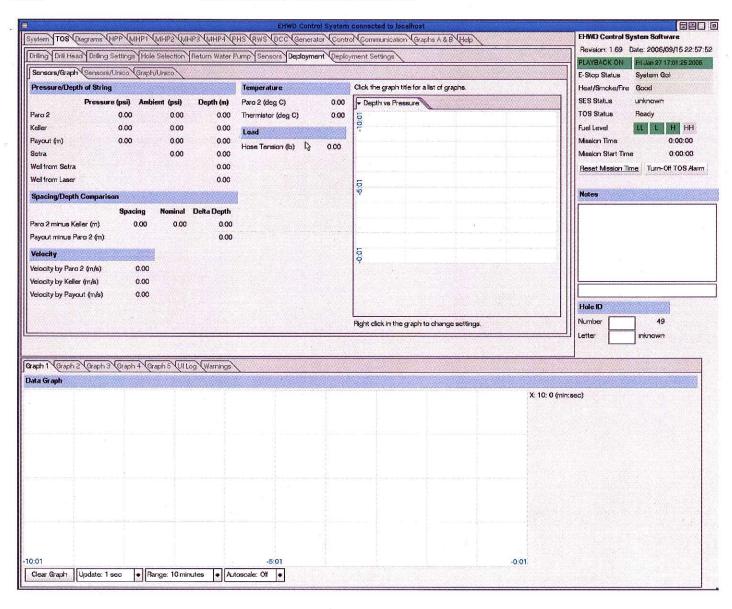
The deployment velocity calculated from recent pressure/payout readings.

Temperature

Temperature readings.

Load

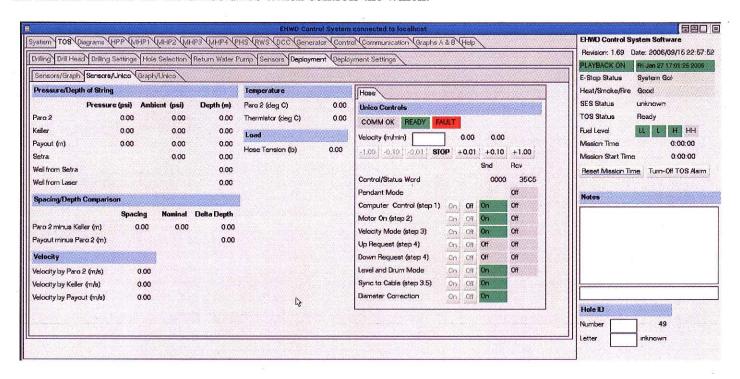
Cable tension from load cell data.



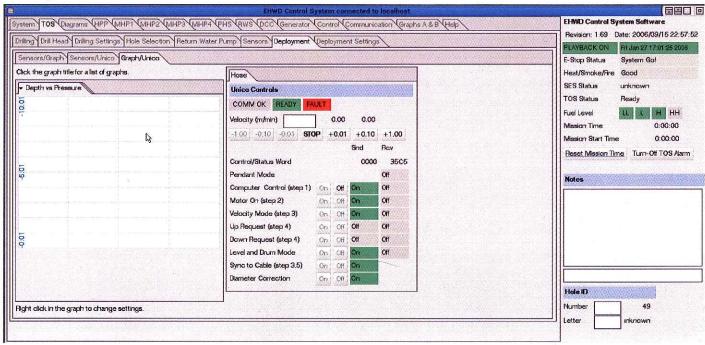
Screen Tab: TOS ▶ Deployment

▶ Sensors/Unico

This tab has the same data display as the main Sensors/Graph tab above, but instead of the graph window this tab has the controls for the Unico drive which controls the winch.



▶ Graph/Unico



Screen Tab: TOS ▶ Deployment Settings

Settings

This is the main tab for entering information that is needed for a correct depth calibration of the pressure data. Make sure you understand what all the entries mean before deployment starts.

Tower Mode

Click on "Deployment".

Deployment Events

Click the appropriate button when one of the predefined events occurs (see list below).

DDB Mode

Select the correct DDB ID before deployment startup (needed for Keller calibration).

Payout at Tower

Reset payout when bottom DOM is at tower floor level. Well Depth Selection Select source of well depth used in depth calculation.

Ambient Pressures

Press "Get" when pressure sensor is attached to cable, or enter reading at that time.

Nominal Spacing

Enter calculated distance between Paro and Keller.

Distances

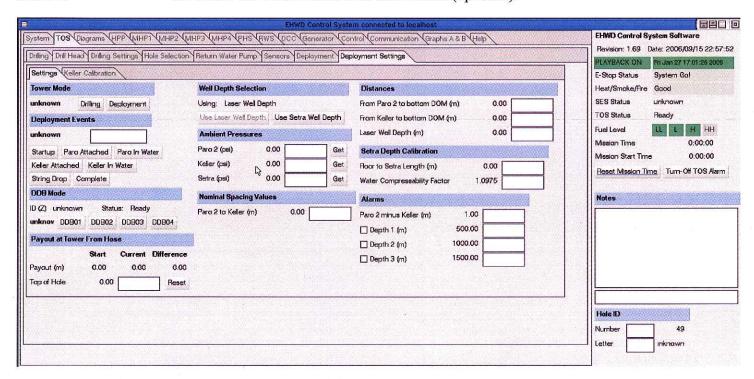
Enter calculated distances between Paro/Keller and DOM60, and well depth.

Setra Depth Calib.

Enter measured length of Setra cable, from floor to sensor.

Alarms

Set values for which alarm is to be sounded (optional).



Deployment Events

☐ Paro In Water

☐ Startup Click when the deployment begins.

☐ Paro Attached Click when the Paro is attached to the breakout and starts sending data.

Click when the Paro reaches the water.

☐ Keller Attached Click when the Keller is attached to the breakout and starts sending data.

☐ Keller In Water Click when the Keller reaches the water.

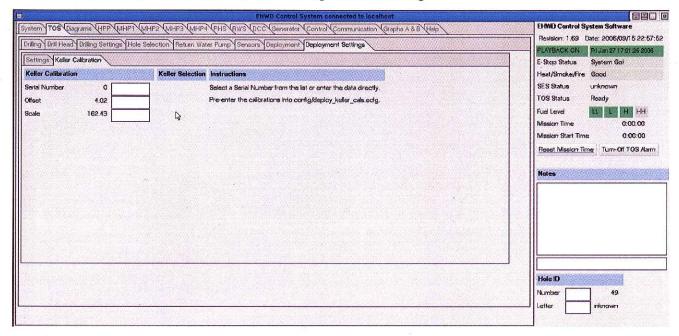
☐ String Drop Click when the String Drop phase begins, after all DOMs have been attached.

☐ Complete Click when the deployment ends (string is secured, etc).

Screen Tab: TOS ▶ Deployment Settings

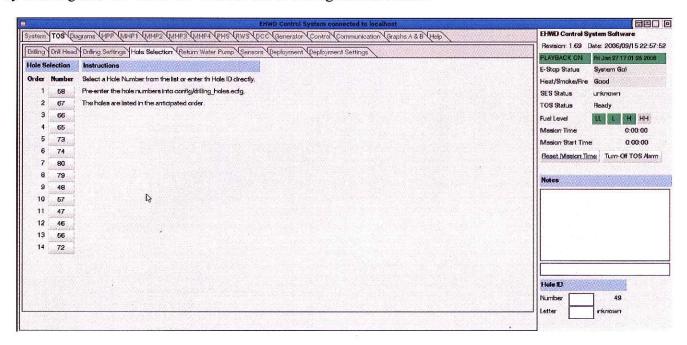
▶ Keller Calibration

On this tab you select the Keller ID by clicking on the appropriate button. The correct (pre-programmed) calibration constants will then be used for the Keller pressure reading.



Screen Tab: TOS ▶ Hole Selection

On this tab you select the hole/string number, *either* by clicking on the numbered button on the left *or* by entering it in the "Hole ID" field in the lower right hand corner.



Distances between devices calculate manually and enter on Deployment Settings tab

Distance between Paro and DOM60:	#	=
Distance between Keller and DOM60:	S 2 5	=
Distance between Paro and Keller:		=

Notes:

There are 60 DOMs on every string.

The nominal spacing between DOMs is 17 m.

The nominal spacing between breakouts is 34 m.

Breakouts (1-30) and DOMs (1-60) are counted from the top.

The Keller is at breakout 15, just above DOM29.

The Paro is at breakout 30, just above DOM59.

(Fun Fact: There used to be a second Paro at breakout 1 on the first four strings)

Pressure conversions

		PSI	mH_2O	Atm
1 PSI	=	1	0.70	0.07
1 mH ₂ O	=	1.4	1	0.1
1 atm	=	14.7	10.3	1

Check Sheet

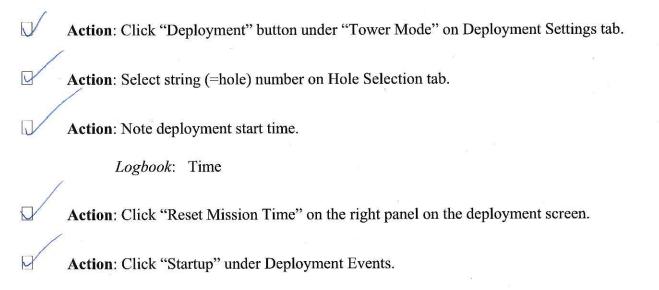
STRING # 47

DATE: 1/22/07

Before Deployment

X	Action: Locate laser ranger for well depth measurements.		
X	Action: Locate metric tape measure.		
	Action: Locate one Paro and one Keller, plus spares of each. need 1 keller		
X	Action: Locate bucket (for cooling of Keller sensor with water/ice mix).		
X	Action: Fill bucket with snow and place in heated area to make slush.		
	Action: Locate Setra uphole pressure assembly (sensor + cable).		

Deployment Startup



IceCube String Deployment Monitoring
Action: Note DDB id number (1, 2, 3, or 4).
ENTER: DDB# (select button)
Logbook: DDB#
Action: Take a well depth measurement with the laser ranger.
ENTER: Well depth [m] will do lathy est. 47.5 m, but too fifty
Logbook: Well depth
Action: Reset Payout when DOM60 breaks the plane of the floor.
CLICK : "Reset" button (Top of Hole Reset) on Deployment Settings ▶ Settings tab.
Logbook: Payout Start value
Action: Get cable mark reading at DOM59.
Logbook: Cable mark [m] 1.5
Action: Attach Paro at breakout #30. (This is called "Paro2" on the monitoring screen).
Logbook: Paro serial number 98/72

Action: Click "Paro Attached" under Deployment Events.

Action: Measure distance between Paro location and nearest DOM. 1.055 m above DOM 59

Estimate distance to *bottom* DOM by adding *n* 17-meter segments (*n* should be 1 for the Paro since nearest DOM is #59). 1.055 + 17.132 = 1.055 + 17.132 = 1.055 + 17.132 = 1.055 + 17.132 = 1.055 + 17.132 = 1.055 + 17.132 = 1.055 + 17.132 = 1.055 + 17.132 = 1.055 + 17.132 = 1.055 + 17.132 = 1.055 + 17.132 = 1.055 + 17.132 = 1.055 + 17.132 = 1.055 + 17.132 = 1.055 + 17.132 = 1.055 + 17.132 = 1.055 + 17.132 = 1.055 + 17.132 = 1.055 + 17.132 = 1.055 + 17.132 = 1.055 + 17.132 = 1.055 + 17.132 = 1.055 + 17.132 = 1.055 + 17.132 = 1.055 + 17.132 = 1.055 + 17.132 = 1.055 + 17.132 = 1.055 + 17.132 = 1.055 + 17.132 = 1.055 + 17.132 = 1.055 + 17.132 = 1.055 + 17.132 = 1.055 + 17.132 = 1.055 + 17.132 = 1.055 + 17.132 = 1.055 + 17.132 = 1.055 + 17.132 = 1.055 + 17.132 = 1.055 + 17.132 = 1.055 + 17.132 = 1.055 + 17.132 = 1.055 + 17.132 = 1.055 + 17.132 = 1.055 + 17.132 = 1.055 + 17.132 = 1.055 + 17.132 = 1.055 + 17.132 = 1.055 + 17.132 = 1.055 + 17.132 = 1.055 + 1.055 + 1.055 + 1.055 + 1.055 + 1.055 + 1.055 + 1.055 + 1.055 + 1.055 + 1.055 + 1.055 + 1.055 + 1.055 + 1.055 + 1.055 + 1.055 + 1.055 + 1.055 + 1.055 + 1.055 + 1.055 + 1.055 + 1.055 + 1.055 + 1.055 + 1.055 + 1.055 + 1.055 + 1.055 + 1.055 + 1.055 + 1.055 + 1.055 + 1.055 + 1.055 + 1.055 + 1.055 + 1.055 + 1.055 + 1.055 + 1.055 + 1.055 + 1.055 + 1.055 + 1.055 + 1.055 + 1.055 + 1.055 + 1.055 + 1.055 + 1.055 + 1.055 + 1.055 + 1.055 + 1.055 + 1.055 + 1.055 + 1.055 + 1.055 + 1.055 + 1.055 + 1.055 + 1.055 + 1.055 + 1.055 + 1.055 + 1.055 + 1.055 + 1.055 + 1.055 + 1.055 + 1.055 + 1.055 + 1.055 + 1.055 + 1.055 + 1.055 + 1.055 + 1.055 + 1.055 + 1.055 + 1.055 + 1.055 + 1.055 + 1.055 + 1.055 + 1.055 + 1.055 + 1.055 + 1.055 + 1.055 + 1.055 + 1.055 + 1.055 + 1.055 + 1.055 + 1.055 + 1.055 + 1.055 + 1.055 + 1.055 + 1.055 + 1.055 + 1.055 + 1.055 + 1.055 + 1.055 + 1.055 + 1.055 + 1.055 + 1.055 + 1.055 + 1.055 + 1.055 + 1.055 + 1.055 + 1.055 + 1.055 + 1.055 + 1.055 + 1.055 + 1.055 + 1.055 + 1.055 + 1.055 + 1.055 + 1.055 + 1.055 + 1.055 + 1.055 + 1.055 + 1.055 + 1.055 + 1.055 + 1.055 +

ENTER: Distance [m] from Paro to bottom DOM (#60)

Logbook: Distance to nearest DOM, nearest DOM#, estimated distance to DOM60

Action: Get cable mark reading at Paro.

Logbook: Cable mark [m] $\approx 2 \, \text{m}$

IceCube String Deployment Monitoring

Action: Take Paro air pressure reading just before it breaks the water surface.

ENTER: Ambient pressure [PSI] for Paro

10.07

Logbook: Paro2 air pressure

During Deployment

Action: Click "Paro In Water" under Deployment Events.

Action: Measure curved distance of main cable going around DOM (for at least two DOMs).

Logbook: Straight (vertical) distance for DOM segment, curved cable distance

Action: Measure real distance between neighboring DOMs (for every pair) with laser ranger.

Logbook: DOM#'s, distance

Action: Put Keller (and one spare) in bucket of water (at near freezing temperature) at least one hour before breakout #15 is reached.

Note: The Keller is not temperature corrected and must therefore be brought to the temperature of the water in the hole (0-2°C) before the air pressure offset is determined.

Action: Attach Keller at breakout #15.

ENTER: Keller serial number

0606746

Logbook: Keller serial number

Action: Click "Keller Attached" under Deployment Events.

Action: Measure distance between Keller and nearest DOM.

Estimate distance to *bottom* DOM by adding n 17-meter segments (n should be 31 for Keller since nearest DOM is #29).

6976 m+31x17= 527.976

ENTER: Distance [m] from Keller to bottom DOM (#60)

Logbook: Distance to nearest DOM, nearest DOM#, estimated distance to DOM60

	IceCube String Deployment Monitoring
	Action: Get cable mark reading at Keller.
/	Logbook: Cable mark [m] for Keller
	Action: Determine Keller air pressure offset before (or just as) Keller hits water.
	ENTER: Ambient pressure [PSI] for Keller
/	Logbook: Ambient Keller pressure
	Action: Click "Keller In Water" under Deployment Events.
	Action: Get cable mark reading at top DOM.
/	Logbook: Cable mark [m]
0	Action: Measure well depth as soon as top DOM is under water.
	ENTER: Well depth [m]
	Logbook: Well depth [m], measurement method (laser/tape)
	Between DOM attachment and String Drop
	Action: Lower Setra assembly into hole (after top DOM is at least 50 m under the surface).
	Action: Measure distance between Setra sensor and floor of tower (distance marked on cable).
	ENTER: Distance Setra to floor [m]
	Logbook: Distance Setra to floor
	Action: Measure well depth with Setra system and laser ranger and compare.
	Logbook: Well depth from Setra [m], well depth from laser [m]
	Action: If the two well depth meaurements agree, switch from laser to Setra in monitoring system.

During String Drop



Action: Click "String Drop" under Deployment Events.



Action: Measure well depth manually (with laser ranger and/or tape measure).

(if shift lead allows: repeat several times during drop)

ENTER: Well depth [m]

Logbook: Well depth, measurement method (laser/tape)



Action: Read cable marks at regular intervals.

Logbook: Cable mark [m]; depth readings [m] (Paro, Keller); time

End of Deployment



Action: Get final pressure readings from Paro and Keller when final depth has been reached.

Logbook: Pressure readings [PSI]; corrected depths [m] (from screen)



Action: Get final well depth reading (laser and/or Setra).

HAS TO BE SIMULTANEOUS WITH FINAL PRESSURE READINGS!

Logbook: Well depth [m] (laser); well depth [m] (Setra)



Action: Note deployment end time.

Logbook: Time



Action: Click "Complete" under Deployment Events.

DOMs for #47

Name	Number	Position
Walrusish	TP4P0313	60
Haihowak	UP6P1424	59
Mariatorget	TP5H0231	58
Seglargrundet	UP5H0254	57
Ensta	TP5H0203	56
Kemps_Card	UP6P1412	55
Kassgrundet	TP5H0121	54
Craits	UP6P1416	53
Ulriksdal	TP5H0249	52
Hapi	UP6Y4382	51
Duat	TP6Y4325	50
Asat	UP6Y4292	49
Svarthakedopping	TP5H0207	48
Kihanga	UP6Y4252	47
Tepoztecatl	TP6Y4361	46
Knipa	UP5H0150	45
Kungsfiskare	TP5H0127	44
Skata	UP5H0132	43
Huracan	TP6Y4307	43
	UP6Y4234	42
Engai Bondkobben		40
	TP5H0133	
Tallbit	UP5H0234	39
Tali	TP6Y4391	38
Storlom	UP5H0230	37
Hatmehit	TP6Y4415	36
Ichneumon	UP6Y4258	35
Mehit	TP6Y4423	34
Cheper	UP6Y4402	33
Albrecht Karle	XXXXXX	32
Li_Tiekuai	UP6Y4448	31
Ahmakiq	TP6Y4245	30
Gla	UP6Y4254	29
Pangu	TP6Y4451	28
Orunmila	UP6Y4256	27
Nchienge	TP6Y4321	26
Celsiusgatan	UP6H7522	25
Pemba	TP6Y4407	24
Kadesch	UP6Y4398	23
Соуора	TP6Y4279	22
Yum_Xac	UP6Y4282	21
Hayagriva	TP6Y4419	20
Alkekung	UP5H0190	19
Top_Trumps	TP6P1417	18
Kali	UP6Y4314	17
Cumhau	TP6Y4283	16
Sixty_three	UP6P1388	15
Fiskekobb	TP5H0227	14
Fingerbulen	UP5H0228	13

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Li_No_cha	TP6Y4467	12
Benben	UP6Y4426	11
Bingo_Card	TP6P1397	10
Cakulha	UP6Y4288	9
Gulkobben	TP5H0145	8
Fong_Tsai	UP6Y4370	. 7
Crazy_Eights	TP6P1405	6
Makaras	UP6Y4248	5
Xochipilli	TP6Y4337	4
Hun_Nai	UP6Y4374	3
Ropsten	TP5H0243	2
	UP6H7506	1
Dchi	TP6Y4273	
Moya	TP6Y4319	3)
Eiebt	TP6Y4479	
Nefertem	UP6Y4280	
Amentet	UP6Y4342	
Harachte	UP6Y4420	